# Velodyne LiDAR® Puck Hi-Res HIGH RESOLUTION REAL-TIME LIDAR SENSOR

### Puck Hi-Res

Velodyne LiDAR's Puck Hi-Res is a higher resolution version of the popular Puck and is used in applications that require increased resolution in the point cloud. The Puck Hi-Res has similar performance to the Puck with the key difference being a higher vertical resolution of 1.33°, with an accompanying 20° vertical field of view. The higher resolution enables detection of objects at longer distances at comparable frame sizes. As a result, the Puck Hi-Res provides more detailed views for applications such as autonomous vehicles, surveillance and 3D mapping/imaging, generating up to ~600,000 points/second.

Like the Puck, the Puck Hi-Res has best-in-class power, which enables operation over a wide temperature range. It's use of off-the-shelf components enables enhanced scalability and attractive volume pricing. Like other Velodyne sensors, the Puck Hi -Res has world-class technical support available across North America, Europe & Asia from the world's leading lidar company.



Security

Mapping

# Puck Hi-Res at a glance

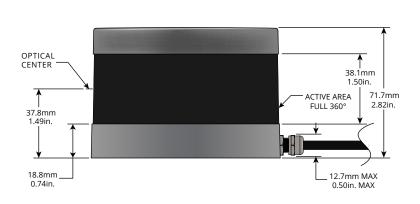
Automotive

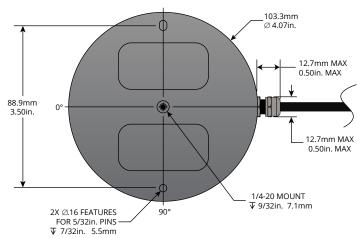
100 m range with compact form factor

Industrial

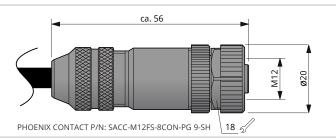
- Higher resolution option in the Puck family
- Proven, Class 1 eye-safe 905 nm technology
- Best-in-class accuracy and calibrated intensity
- Best-in-class power & temperature range
- Sensor-to-sensor interference mitigation feature
- Versatile, with attractive volume pricing

**DIMENSIONS** (Subject to change)





## **M12 CONNECTOR OPTION**



For other connector options contact **Velodyne Sales (sales@velodyne.com)** 

# **High Resolution Real-Time Lidar Sensor**

The Puck Hi-Res provides high definition 3-dimensional information about the surrounding environment.



	Specifications:
Sensor:	<ul> <li>16 Channels</li> <li>Measurement Range: 100 m</li> <li>Range Accuracy: Up to ±3 cm (Typical)<sup>1</sup></li> <li>Field of View (Vertical): +10.0° to -10.0° (20°)</li> <li>Angular Resolution (Vertical): 1.33°</li> <li>Field of View (Horizontal): 360°</li> <li>Angular Resolution (Horizontal/Azimuth): 0.1° – 0.4°</li> <li>Rotation Rate: 5 Hz – 20 Hz</li> <li>Integrated Web Server for Easy Monitoring and Configuration</li> </ul>
Laser:	<ul> <li>Laser Product Classification: Class 1 Eye-safe per IEC 60825-1:2007 &amp; 2014</li> <li>Wavelength: 903 nm</li> </ul>
Mechanical/ Electrical/ Operational	<ul> <li>Power Consumption: 8 W (Typical)<sup>2</sup></li> <li>Operating Voltage: 9 V – 18 V (with Interface Box and Regulated Power Supply)</li> <li>Weight: ~830 g (without Cabling and Interface Box)</li> <li>Dimensions: See diagram on previous page</li> <li>Environmental Protection: IP67</li> <li>Operating Temperature: -10°C to +60°C<sup>3</sup></li> <li>Storage Temperature: -40°C to +105°C</li> </ul>
Output:	<ul> <li>3D Lidar Data Points Generated:         <ul> <li>Single Return Mode: ~300,000 points per second</li> <li>Dual Return Mode: ~600,000 points per second</li> </ul> </li> <li>100 Mbps Ethernet Connection</li> <li>UDP Packets Contain:         <ul> <li>Time of Flight Distance Measurement</li> <li>Calibrated Reflectivity Measurement</li> <li>Rotation Angles</li> <li>Synchronized Time Stamps (µs resolution)</li> </ul> </li> <li>GPS: \$GPRMC and \$GPGGA NMEA Sentences from GPS Receiver (GPS not included)</li> </ul>

63-9318 Rev-F VLP-16-HI-RES

### For more details and ordering information, contact Velodyne Sales (sales@velodyne.com)

- 1. Typical accuracy refers to ambient wall test performance across most channels and may vary based on factors including but not limited to range, temperature and target reflectivity.
- 2. Operating power may be affected by factors including but not limited to range, reflectivity and environmental conditions.
- 3. Operating temperature may be affected by factors including but not limited to air flow and sun load.

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